

Machine Learning Journal Club

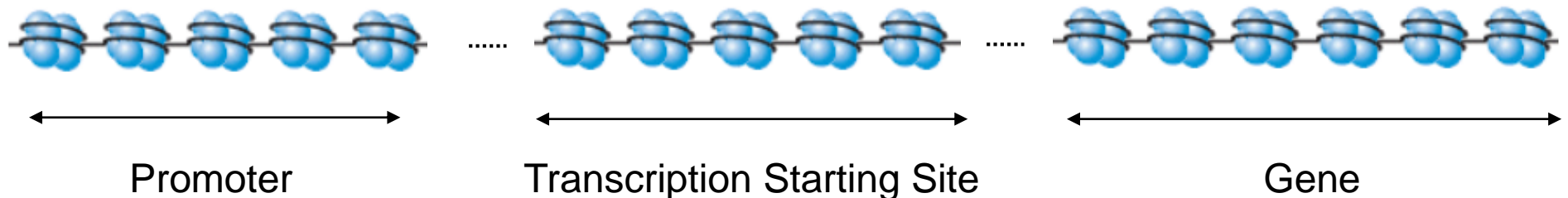
- Introduction to Hidden Markov Models -

Wednesday, June 7th

Baptiste AMELINE, Dyogen team

Markov Models, tools to predict

In biology, the markov models are used to segregate the genome into small fragments sharing common biological features.



As a consequence, Markov models are commonly used to perform genomic annotations from whole genome NGS sequencing (ChIP-seq, Bis-Seq...)

↳ Encode Project, 2012. *Nature*. «An integrated encyclopedia of DNA elements in the human genome»

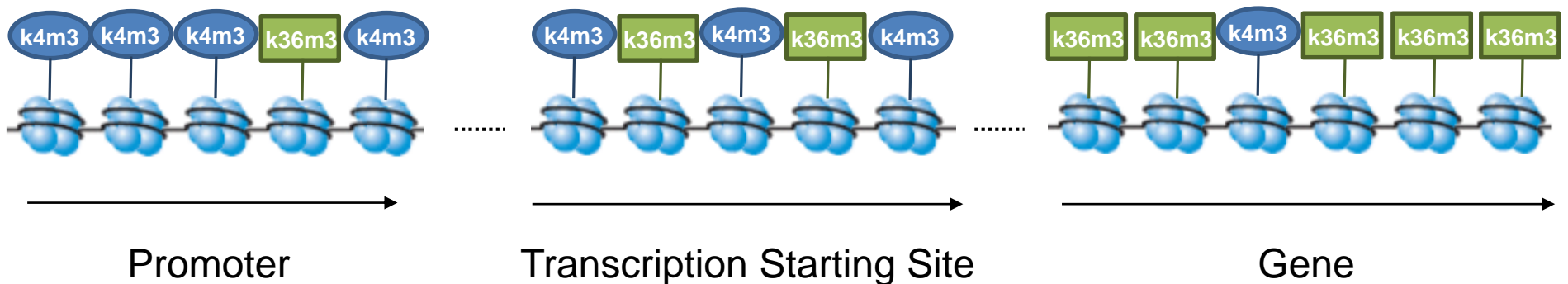
Two main types of Markov Models

- Markov chain -

Definition : It models the state of a system with a random variable (represented by a probability to observe a pattern) that changes through time. Distribution for this variable depends only on the distribution of the previous state.



You split your DNA sequence into different states (promoter, TSS,...), the transition to a new state depends on the current state, and inside a specific state you have a probability to observe your pattern (ex: histon methylation) a little bit different compared to the observation probability in the previous state.

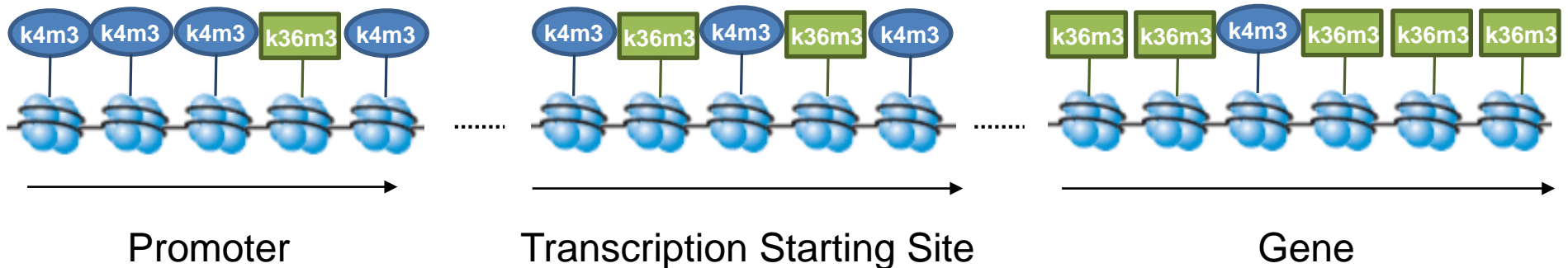
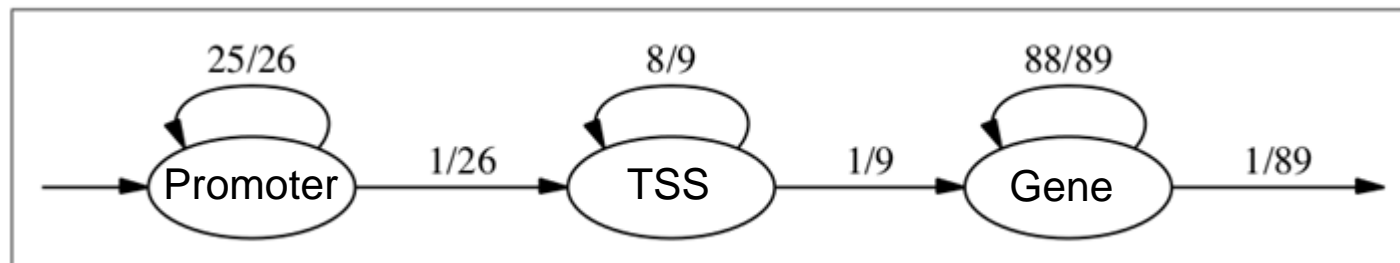


How to rightly describe a model using MM ?

Observations
Probability

	Probability to observe H3K4me3	Probability to observe H3K36me3
Promoter	0.85	0.15
TSS	0.75	0.25
Gene	0.10	0.90


Transitions
Probabilities

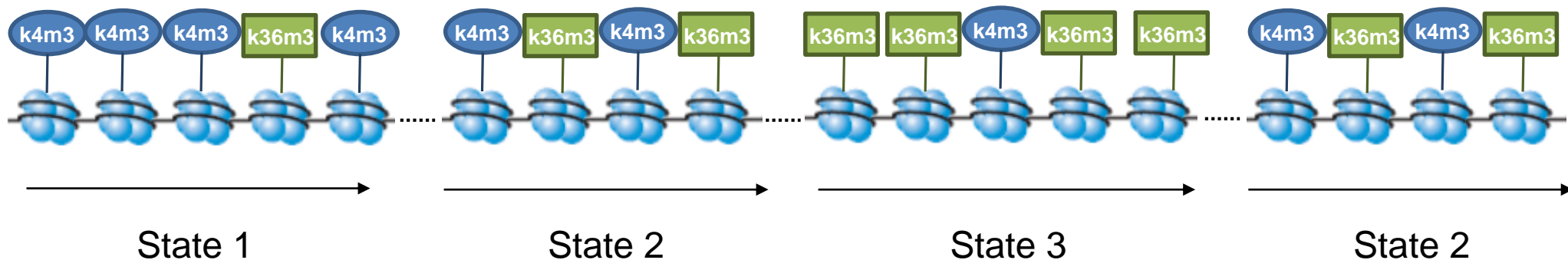


Two main types of Markov Models

- Hidden Markov Models -

Definition : Hidden Markov Model (HMM) is a Markov chain for which the state is only partially observable. In consequence, observations are related to the state of the system, but they are typically insufficient to precisely determine the state.

Maths > Bio  → The model is splitted into different states (number defined by user) according to the distribution of the random variable (observations). All transitions from one state to an other are possible and associated to a transition probability.

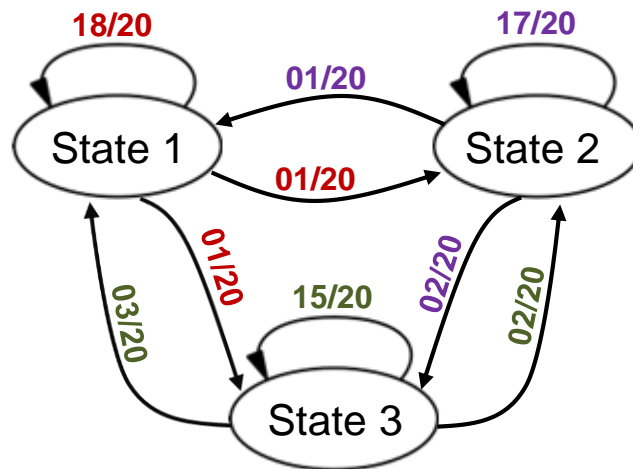


How to rightly describe a model using HMM ?

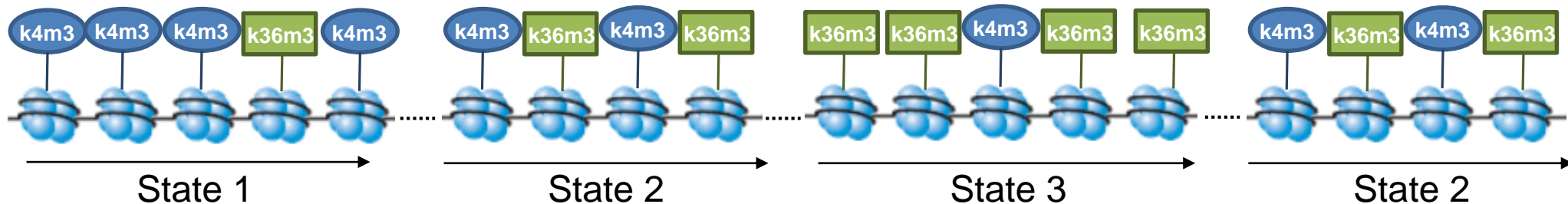
Observations
Probability

	Probability to observe H3K4me3	Probability to observe H3K36me3
State 1	0.85	0.15
State 2	0.75	0.25
State 3	0.10	0.90

Transitions
Probabilities



From \ To	State 1	State 2	State 3
State 1	18/20	01/20	01/20
State 2	01/20	17/20	02/20
State 3	03/20	02/20	15/20



Hidden Markov Models

General description

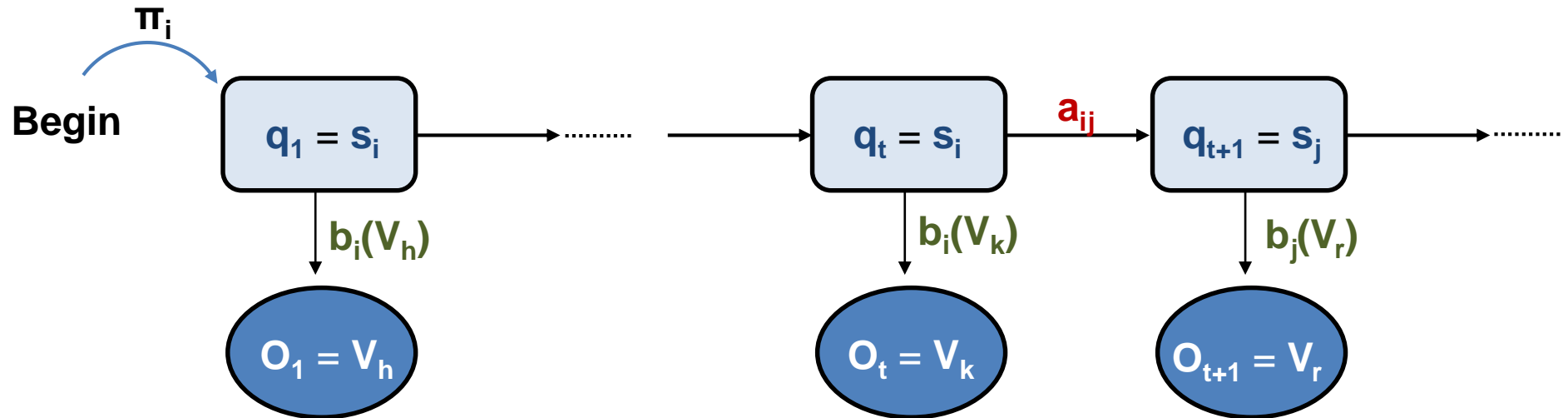
A « basic » hidden markov model can be described as follows:

n	= number of states
$S = \{s_1, s_2, \dots, s_n\}$	= the different states
$V = \{v_1, v_2, \dots, v_M\}$	= alphabet of observations
A	= matrix of probabilities of transition
$a_{ij}, i, j \in [1, n]$	= probability of transition from state i to state j
B	= matrix of probabilities of observation
$b_j(k), j \in [1, n], k \in [1, M]$	= probability of observation of k, in the state j
π	= vector of initial probability
$\Lambda = (A, B, \pi)$	= minimal description of a HMM model
T	= Length of an observed sequence
$O = O_1 \dots O_t \dots O_T$ $O_t \in V$	= an observed sequence
$O(i : j) = O_i \dots O_j$	= sub-sequence
$q_1 \dots q_t \dots q_T : q_t \in S$	= the series of states that have emitted the sequence
$P(O \mid \Lambda)$	= probability to observed a sequence O given the HMM Λ
$\mathcal{O} = \mathcal{O}^1 \dots \mathcal{O}^m$	= a series of m sequences of observations
$P(\Lambda \mid \mathcal{O})$	= probability the HMM Λ emitted the serie of sequences \mathcal{O}

	Obs1	Obs2
S1	$B_1(O_1)=0.85$	$B_1(O_2)=0.15$
S2	$B_2(O_1)=0.75$	$B_2(O_2)=0.25$
S3	$B_3(O_1)=0.10$	$B_3(O_2)=0.90$

To \ From	S1	S2	S3
S1	$a_{11}=18/20$	$a_{12}=01/20$	$a_{13}=01/20$
S2	$a_{21}=01/20$	$a_{22}=17/20$	$a_{23}=02/20$
S3	$a_{31}=03/20$	$a_{32}=02/20$	$a_{33}=15/20$

Generate a sequence with a HMM



Begin

$t \leftarrow 1$

Choose an initial state $q_1 = s_i$ with a probability π_i

While $t \leq T$

 Choose observation $o_t = v_k$ with a probability $b_i(k)$

 Switch to next state $q_{t+1} = s_j$ with a probability a_{ij}

$t \leftarrow t + 1$

End while

End

Hidden Markov Models

- Three main applications of Hidden Markov Models -

Training of the model.

Considering a series of sequences Θ , you adjust the parameters of the model $\Lambda(A, B, \pi)$, to maximize : $P(O | \Lambda) = \prod_{O \in \Theta} P(O | \Lambda)$

Evaluation of the probability of observation of a sequence.

Given an observed sequence O and an HMM $\Lambda(A, B, \pi)$, you apply a maximum likelihood strategy to estimate the probability of observation.

Searching for the most likely sequence of hidden states.

Given an observation sequence O and an HMM $\Lambda(A, B, \pi)$, you apply a maximum likelihood strategy to estimate the probability of observation.

Hidden Markov Models

- Evaluation of the probability of observation of a sequence -

→ A sequence of observation O can be built using Q different pathways of a model Λ , whose the likelihoods greatly varies. Thus the probability to observe the sequence O is the sum of probabilities of all the Q differents pathways.

$$P(O | \Lambda) = \sum_Q P(O | Q, \Lambda) P(Q | \Lambda)$$

where

$$P(Q | \Lambda) = \pi_{q_1} a_{q_1 q_2} a_{q_2 q_3} \dots a_{q_{T-1} q_T}$$

$$P(O | Q, \Lambda) = b_{q_1}(O_1) b_{q_2}(O_2) \dots b_{q_T}(O_T)$$

— —→

transition sequence of the pathway q

— Powered by Google Translate —→

observation sequence of the pathway q



$$P(O | \Lambda) = \sum_{Q=q_1, q_2, \dots, q_T} \pi_{q_1} b_{q_1}(O_1) a_{q_1 q_2} b_{q_2}(O_2) \dots a_{q_{T-1} q_T} b_{q_T}(O_T)$$

Considering the Q pathways of length T , the complexity is $O(Q^T)$

Hidden Markov Models

- Evaluation of the probability of observation of a sequence -

→ The « Forward – backward algorithm » reduces the complexity to $O(n^2T)$

$$P(O | \Lambda) = \sum_{i=1}^n \alpha_t(i) \beta_t(i)$$

Probability to observe the beginning (1 : t)
 $\alpha_t(i) = P(O_1 O_2 \dots O_t, q_t = s_i | \Lambda)$

Probability to observe the end (t+1 : T)
 $\beta_t(i) = P(O(t+1 : T), q_{t+1} = s_i | \Lambda)$

Begin

For $i = 1 : n$; **Do** $\alpha_1(i) \leftarrow \pi_i b_i(O_1)$

$t \leftarrow 1$

While $t \leq T$

$j \leftarrow 1$

While $j \leq n$

$\alpha_{t+1}(j) \leftarrow [\sum_{i=1}^n \alpha_t(i) a_{ij}] b_j(O_{t+1})$

$j \leftarrow j + 1$

End while

$t \leftarrow t + 1$

End while

$P(O | \Lambda) \leftarrow \sum_{i=1}^n \alpha_T(i)$

End

Forward

Begin

For $i = 1 : n$; **Do** $\beta_T(i) \leftarrow 1$

$t \leftarrow T - 1$

While $t \geq 1$

$i \leftarrow 1$

While $i \leq n$

$\beta_t(i) \leftarrow \sum_{j=1}^n a_{ij} b_j(O_{t+1}) \beta_{t+1}(j)$

$i \leftarrow i + 1$

End while

$t \leftarrow t - 1$

End while

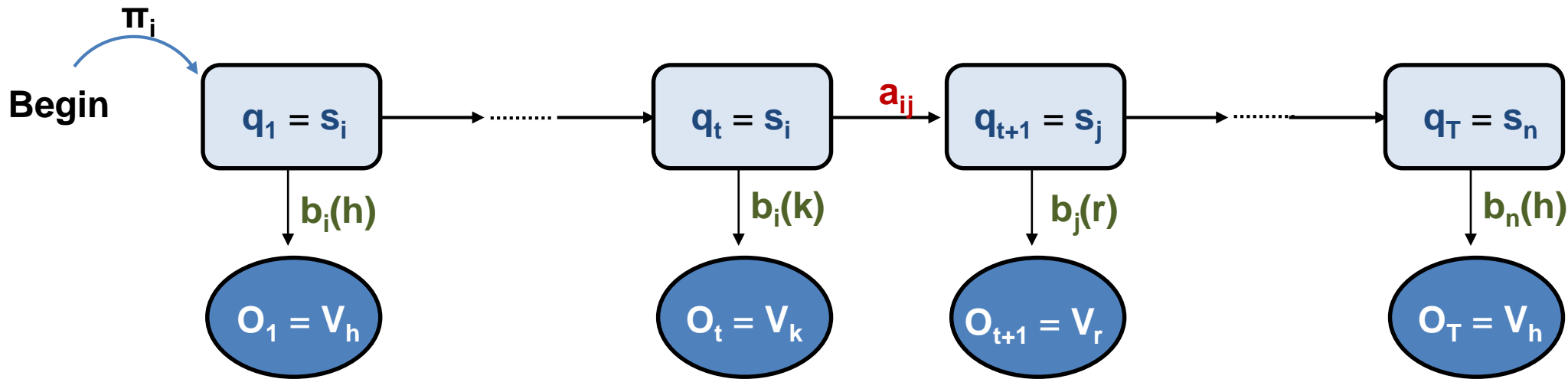
$P(O | \Lambda) \leftarrow \sum_{i=1}^n \beta_1(i)$

End

Backward

Hidden Markov Models

- Evaluation of the probability of observation of a sequence -



Begin

For $i = 1 : n$; Do $\alpha_1(i) \leftarrow \pi_i b_i(O_1)$

$t \leftarrow 1$

While $t \leq T$

$j \leftarrow 1$

 While $j \leq n$

$\alpha_{t+1}(j) \leftarrow [\sum_{i=1}^n \alpha_t(i) a_{ij}] b_j(O_{t+1})$

$j \leftarrow j + 1$

 End while

$t \leftarrow t + 1$

End while

$P(O | \Lambda) \leftarrow \sum_{i=1}^n \alpha_T(i)$

End

Forward

Begin

For $i = 1 : n$; Do $\beta_T(i) \leftarrow 1$

$t \leftarrow T - 1$

While $t \geq 1$

$i \leftarrow 1$

 While $i \leq n$

$\beta_t(i) \leftarrow \sum_{j=1}^n a_{ij} b_j(O_{t+1}) \beta_{t+1}(j)$

$i \leftarrow i + 1$

 End while

$t \leftarrow t - 1$

End while

$P(O | \Lambda) \leftarrow \sum_{i=1}^n \beta_1(i)$

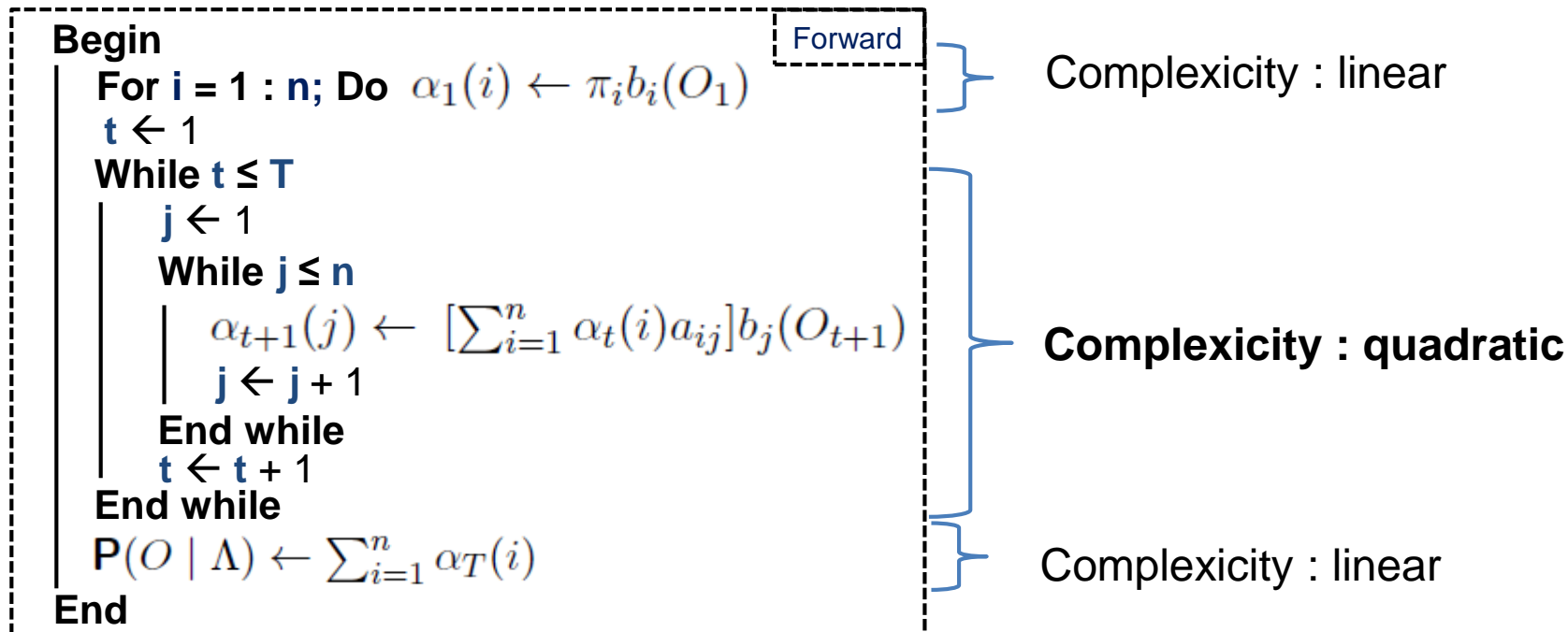
End

Backward

Hidden Markov Models

- Evaluation of the probability of observation of a sequence -

→ Reduction of the complexity is based on the assumption that we only need the information of the previous state to predict the next one.




Hidden Markov Models

- Searching for the most likely sequence of hidden states -

→ A sequence of observation \mathbf{O} can be built using Q different pathways of a model Λ , whose the likelihoods greatly vary. Viterbi algorithm gives the state sequence \mathbf{q} which maximize the probability of observation $P(\mathbf{Q}, \mathbf{O} \mid \Lambda)$.

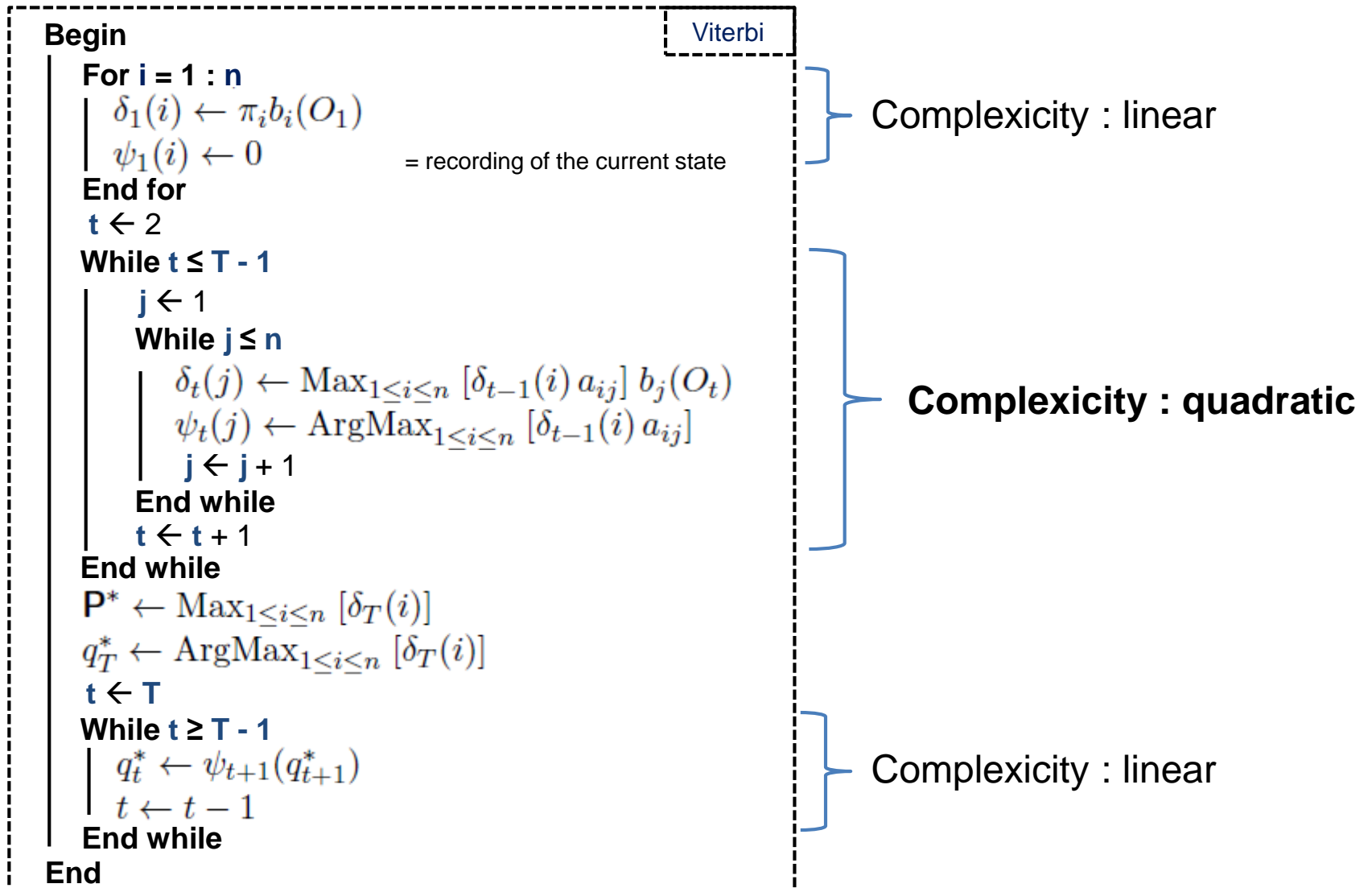
Let's define $\delta_t(i)$ as : $\delta_t(i) = \underset{q_1, \dots, q_{t-1}}{Max} \mathbf{P}(q_1, q_2, \dots, q_t = s_i, O_1, O_2, \dots, O_t \mid \Lambda)$


 Best pathway to reach the q_t element

By recurrence, we can set : $\delta_{t+1}(j) = [\underset{i}{Max} \delta_t(i) a_{ij}] b_j(O_{t+1})$

Hidden Markov Models

- Evaluation of the probability of observation of a sequence -



Hidden Markov Models

- Training of the model -

→ In absence of information, initialization of the model Λ^0 (A^0 , B^0 , π^0) starts with:

- Equiprobability to switch from a state to an other :

π^0

From \ To	S1	S2	S3
π	$\pi_1=1/3$	$\pi_2=1/3$	$\pi_3=1/3$

A^0

From \ To	S1	S2	S3
S1	$a_{11}=1/3$	$a_{12}=1/3$	$a_{13}=1/3$
S2	$a_{21}=1/3$	$a_{22}=1/3$	$a_{23}=1/3$
S3	$a_{31}=1/3$	$a_{32}=1/3$	$a_{33}=1/3$

- Probabilities of observation set according to the frequency of observations of the pattern in the dataset.

B^0

	Obs1	Obs2
S1	$B_1(O_1)=\text{obs1} / (\text{obs1}+\text{obs2})$	$B_1(O_2)=\text{obs2} / (\text{obs1}+\text{obs2})$
S2	$B_2(O_1)=\text{obs1} / (\text{obs1}+\text{obs2})$	$B_2(O_2)=\text{obs2} / (\text{obs1}+\text{obs2})$
S3	$B_3(O_1)=\text{obs1} / (\text{obs1}+\text{obs2})$	$B_3(O_2)=\text{obs2} / (\text{obs1}+\text{obs2})$

Hidden Markov Models

- Training of the model -

Training of the model.

Considering a series of sequences Θ , you adjust the parameters of the model $\Lambda(A, B, \pi)$, to maximize : $P(\Theta | \Lambda) = \prod_{O \in \Theta} P(O | \Lambda)$

Viterbi algorithm on $\Lambda^0(A^0, B^0, \pi^0)$

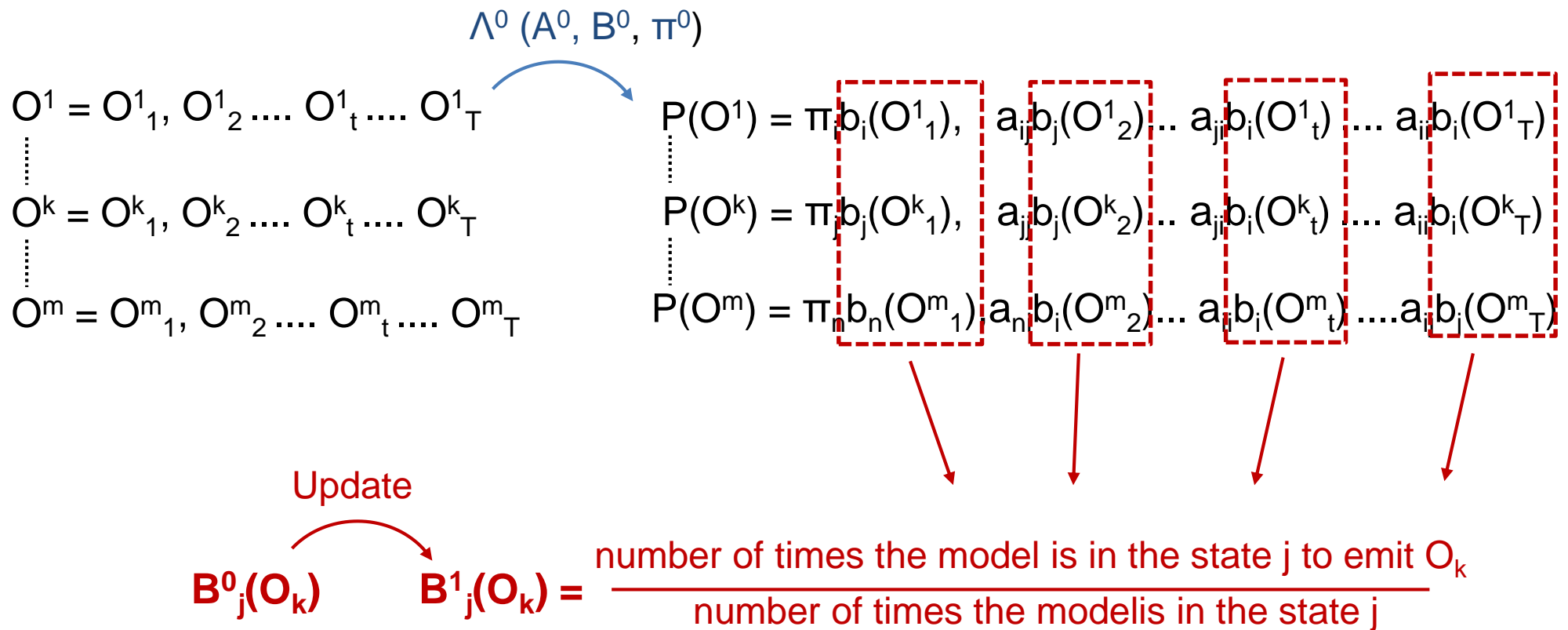
$$\begin{array}{l}
 O^1 = O^1_1, O^1_2 \dots O^1_t \dots O^1_T \\
 \vdots \\
 O^k = O^k_1, O^k_2 \dots O^k_t \dots O^k_T \\
 \vdots \\
 O^m = O^m_1, O^m_2 \dots O^m_t \dots O^m_T
 \end{array}
 \quad
 \begin{array}{l}
 P(O^1) = \pi_i b_i(O^1_1), a_{ij} b_j(O^1_2) \dots a_{ji} b_i(O^1_t) \dots a_{ij} b_i(O^1_T) \\
 \vdots \\
 P(O^k) = \pi_j b_j(O^k_1), a_{jj} b_j(O^k_2) \dots a_{ji} b_i(O^k_t) \dots a_{ij} b_i(O^k_T) \\
 \vdots \\
 P(O^m) = \pi_n b_n(O^m_1), a_{ni} b_i(O^m_2) \dots a_{ij} b_j(O^m_t) \dots a_{ij} b_j(O^m_T)
 \end{array}$$

Update

$$\pi^0_i \rightarrow \pi^1_i = \frac{\text{number of times the model is in the state } i \text{ to emit } O_1}{\text{number of times the model emits } O_1}$$

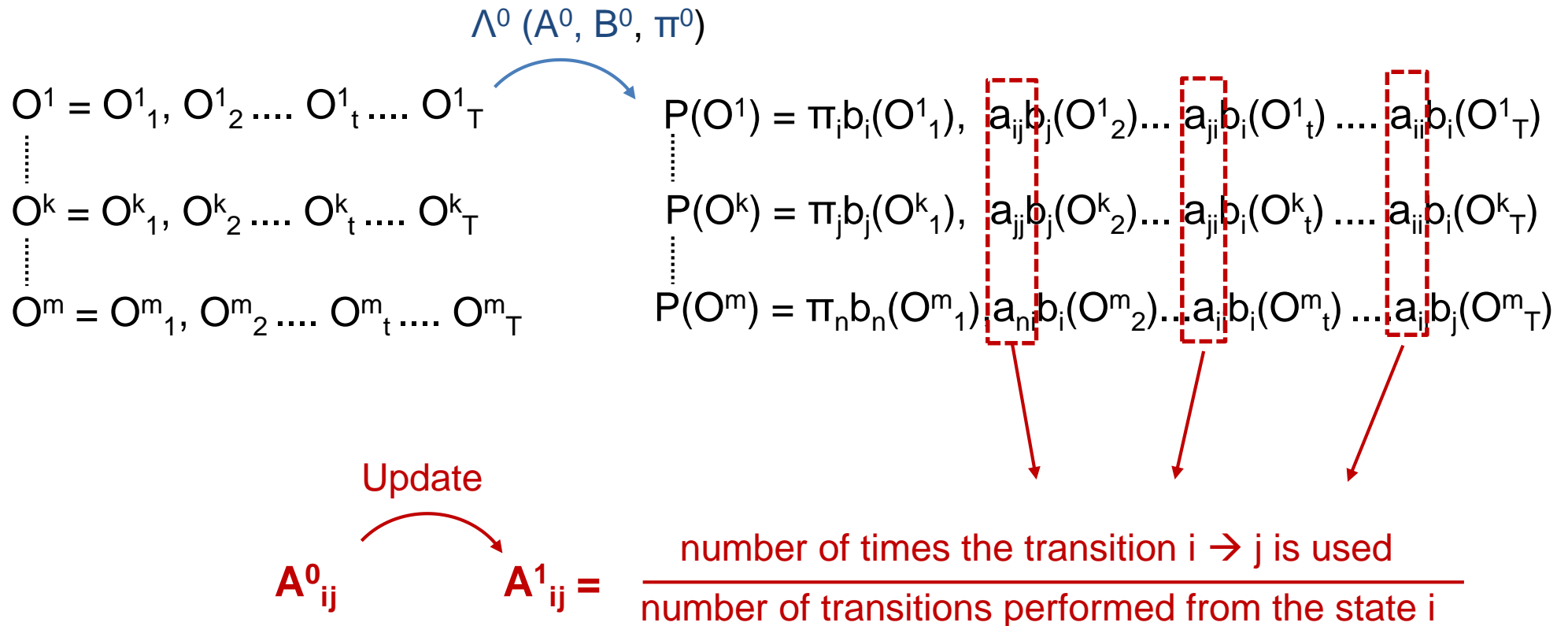
Hidden Markov Models

- Training of the model -



Hidden Markov Models

- Training of the model -

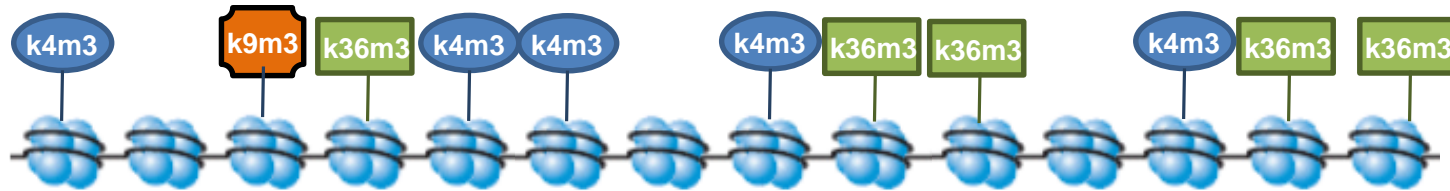


Implementation of this strategy : Algorithm of Baum-Welch

(special case of the Expectation Maximization algorithm for the adjustment of the HMM parameters)

Hidden Markov Models

- **ChromHMM** : user (rather) friendly package to apply HMM strategy -



- Considering you have a dataset composed of different ChIP-seq covering (a part of) the genome, by setting a number of expected states, you can :

1. Train your model and define the parameters (A , B , π) of your HMM Λ using a first replicate.

π

From \ To	S1	S2	S3
π	π_1	π_2	π_3

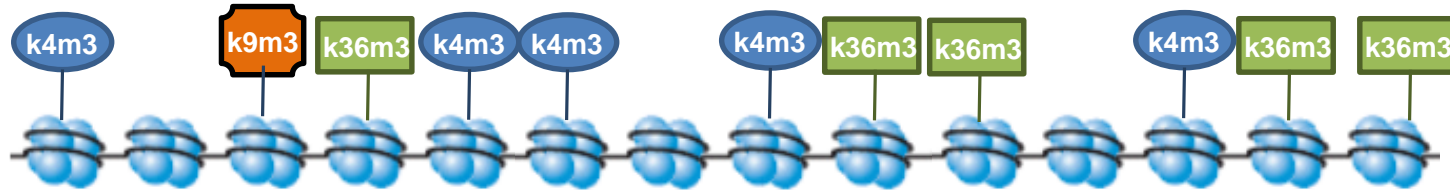
A

From \ To	S1	S2	S3
S1	a_{11}	a_{12}	a_{13}
S2	a_{21}	a_{22}	a_{23}
S3	a_{31}	a_{32}	a_{33}

B

	Obs1	Obs2
S1	$B_1(O_1)$	$B_1(O_2)$
S2	$B_2(O_1)$	$B_2(O_2)$
S3	$B_3(O_1)$	$B_3(O_2)$

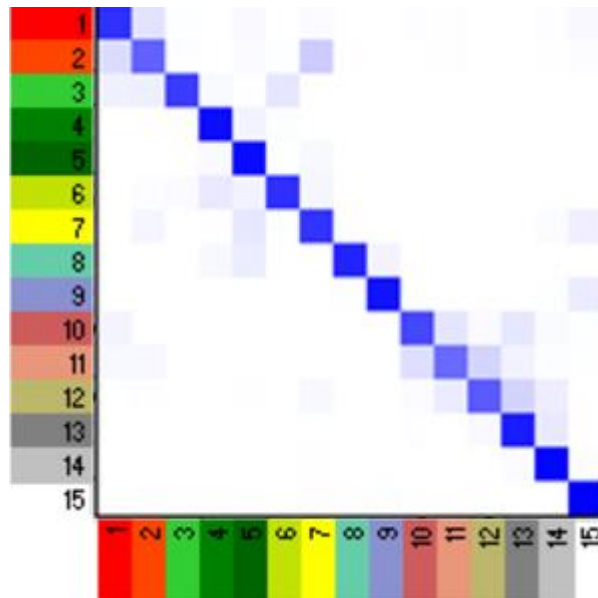
Hidden Markov Models



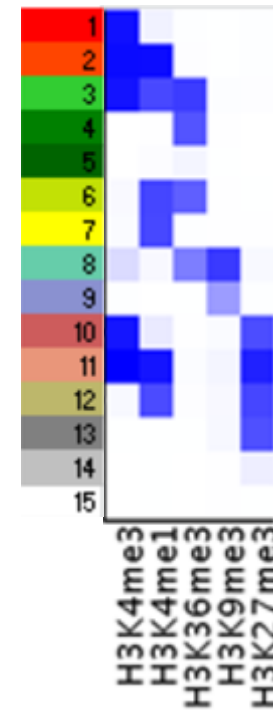
2. Based on a second replicate, search for the sequence of hidden states.

- 15 -states model:

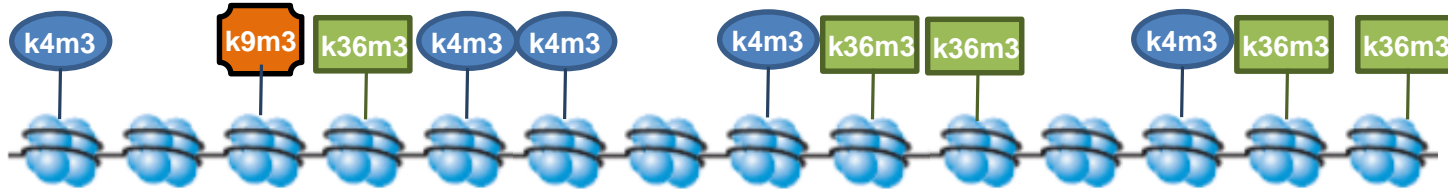
State transition matrix



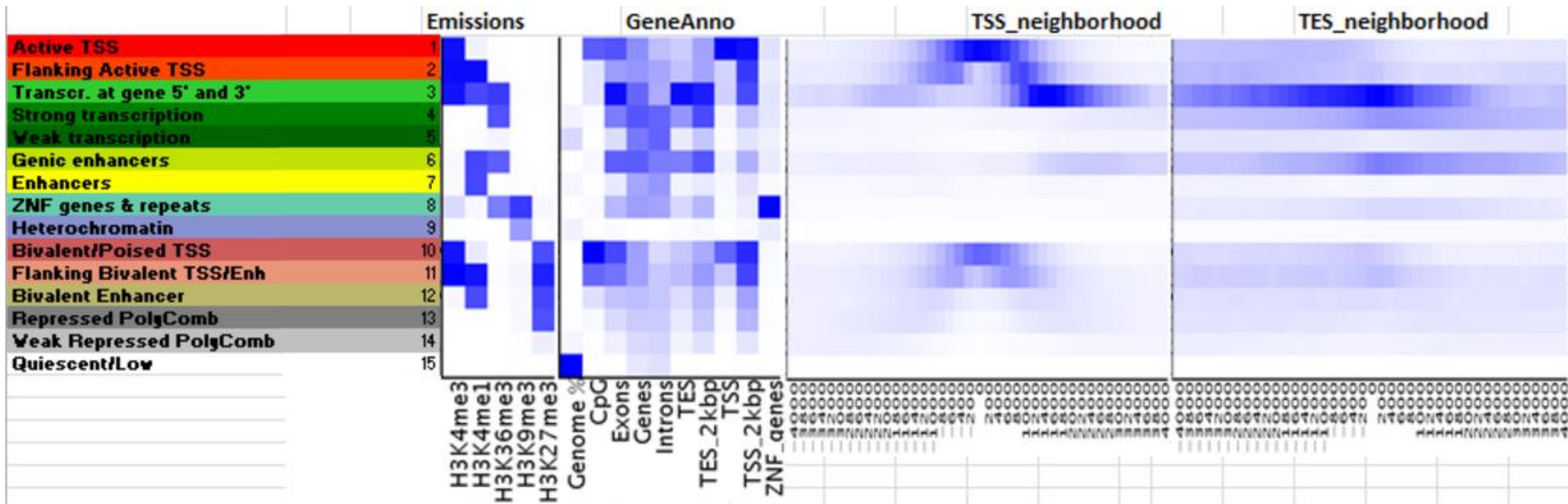
probability obs matrix



Hidden Markov Models



3. Associate your probability observation matrix to genomic annotations to estimate the « biological effect » behind the hidden states .



Do you want more ?

Bioinfo seminar on Thursday, June 22th

« **Toward a fonctionnal map of the human germline genome** »

Thank you to your attention